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RINEX ver2-base QZSS Extension (Version 1.00)

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(JAXA has proposed this RINEX format QZSS Extension to IGS. JAXA hopes this format will become a de fact standard and will be integrated to original RINEX format published by IGS. When this format is integrated to the original RINEX format and published on the IGS website, this format will be abolished.)

(This RINEX format QZSS Extension version is written based on RINEX version 2.12 published by IGS at the moment 17-December-2010)

Contents:

- 0. Revision History
 - 0.1 Revision Summary
 - 0.2 First Revision
 - 0.3 Later Revisions
 - 0.4 Version 2.10 Modifications
 - 0.5 Version 2.10 Revisions
 - 0.6 Version 2.11 Modifications
 - 0.7 Version 2.12 Modifications
 - 0.8 QZSS Extension Modifications
- 1. THE PHILOSOPHY OF RINEX
- 2. GENERAL FORMAT DESCRIPTION
- 3. DEFINITION OF THE OBSERVABLES
- 4. THE EXCHANGE OF RINEX FILES:
- 5. RINEX VERSION 2 FEATURES
 - 5.1 Satellite Numbers:
 - 5.2 Order of the Header Records:

- 5.3 Missing Items, Duration of the Validity of Values
- 5.4 Event Flag Records
- 5.5 Receiver Clock Offset

- 6. ADDITIONAL HINTS AND TIPS
 - 6.1 Version 1 / Version 2
 - 6.2 Leading Blanks in CHARACTER fields
 - 6.3 Variable-length Records
 - 6.4 Blank Fields
 - 6.5 2-Digit Years
 - 6.6 Fit Interval
 - 6.7 Satellite Health
 - 6.8 Transmission Time of Message (Navigation message file)
 - 6.9 Unknown / Undefined Observation Types and Header Records
 - 6.10 Order of data records

- 7. RINEX UNDER ANTISPOOFING (AS)

- 8. GLONASS Extensions
 - 8.1 RINEX Observation File
 - 8.1.1 Time System Identifier
 - 8.1.2 Pseudorange Definition
 - 8.1.3 More Than 12 Satellites per Epoch
 - 8.2 RINEX Navigation Files for GLONASS

- 9. RINEX Extensions for Geostationary Satellites (GPS Signal Payloads)
 - 9.1 RINEX Observation Files for GEO Satellites
 - 9.2 RINEX Navigation Message Files for GEO Satellites

- 10. Version 2.11 Modifications
 - 10.1 Galileo and New GPS Observables
 - 10.1.1 New Observation Codes
 - 10.1.2 Wavelength Factors
 - 10.2 Clarifications in the GEO Navigation Message File
 - 10.3 New observables for RINEX met files

- 11. Version 2.12 Modifications
 - 11.1 Phase Cycle Shifts
 - 11.2 Galileo: BOC-Tracking of an MBOC-Modulated Signal

- 11.3 New Observation Codes for GPS L1C,L2C,L1(C/A), Glonass L1(SA),L2(SA), and Compass
- 11.4 Compass Satellite System Code
- 11.5 Galileo Navigation Message File
- 11.6 Unification of the TIME SYSTEM CORR record
- 11.7 Unification of the IONOSPHERIC CORR record
- 11.8 Order of data records
- 11.9 RINEX Meteorological Data Files

12. Modifications for QZSS

- 12.1 QZSS signals
- 12.2 New Observation Codes for QZSS
- 12.3 PRN Code Numbers for QZSS
- 12.4 QZSS Satellite System Code
- 12.5 QZSS Navigation Message File
- 12.6 Time system on QZSS

13. REFERENCES

APPENDIX: RINEX VERSION 2.12 FORMAT DEFINITIONS AND EXAMPLES

- A 1 GPS OBSERVATION DATA FILE – HEADER SECTION DESCRIPTION
- A 2 GPS OBSERVATION DATA FILE – DATA RECORD DESCRIPTION
- A 3 GPS NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION
- A 4 GPS NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION
- A 5 METEOROLOGICAL DATA FILE – HEADER SECTION DESCRIPTION
- A 5 METEOROLOGICAL DATA FILE – DATA RECORD DESCRIPTION
- A 7 MIXED OBSERVATION DATA FILE – EXAMPLE
- A 8 GPS NAVIGATION MESSAGE FILE – EXAMPLE
- A 9 METEOROLOGICAL DATA FILE – EXAMPLE
- A10 GLONASS NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION
- A11 GLONASS NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION
- A12 GLONASS NAVIGATION MESSAGE FILE – EXAMPLE
- A13 GLONASS OBSERVATION FILE – EXAMPLE
- A14 MIXED GPS/GLONASS OBSERVATION FILE – EXAMPLE
- A15 GEOSTATIONARY NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION
- A16 GEOSTATIONARY NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION
- A17 MIXED GPS/GEO OBSERVATION FILE – EXAMPLE
- A18 GEO NAVIGATION MESSAGE FILE – EXAMPLE
- A19 GALILEO NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION

- A20 GALILEO NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION
- A21 QZSS NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION
- A22 QZSS NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION

0. REVISION HISTORY

0.1 Revision Summary

First Revision, April 1993
Clarification December 1993
Doppler Definition: January 1994
PR Clarification: October 1994
Wlfact Clarification: February 1995
Event Time Frame Clarification: May 1996
Minor errors in the examples A7/A8: May 1996
Naming convention for compressed met files: January 1997
Continuation line clarifications: April 1997
GLONASS Extensions: April 1997
Met sensor description and position records: April 1997
Wavelength factor clarifications: April 1997
Error in example A12: CORR TO SYSTEM TIME, April 1997
Redefinition of sv clock params in GLONASS Nav Mess Files: March 1998
Naming conventions for compressed RINEX obs files: March 1998
GPS week: No roll-over, continuous number: March 1998
Error in compressed DOS file naming convention: July 1998
Table A13 contained blank satellite identifiers: Sept 1998
Discrepancy between Tables A5 and A9 removed: Sept 1998
Phase data format overflow: Clarification: Oct 1998
Message frame time Table A11: Clarification: Oct 1998
RINEX Version 2.10 Modifications: July 1999
Typo in paragraph 0.4 (epoch flag >1): Nov 1999
Clarification regarding trailing blanks: Dec 1999
Clarification regarding units of ZD,ZT, URA(GEO)
Clarification regarding time system identifier of GEO obs files
Clarification regarding time system identifier in TIME OF LAST record: Feb 2000
Addition of GEO examples: February 2000
Clarification of epoch field for event flag records: May 2000
Table A6: Typos in format definition of epoch: May 2000
Clarification of the GLONASS satellite identifier: June 2001
Clarification of the floating point exponent format: January 2002

RINEX Version 2.11 modifications: October 2004

Some clarifications in the GEO D-UTC A0, A1, T, W, S, U record November 2005

Wind, rain and hail observables in met files: December 2005

Unknown/undefined observation types and header records: December 2005

References to clock and SBAS RINEX files. Extended filenames: December 2005

Header continuation lines have to include the respective header label

Glonass frequency numbers -7 ... +13: December 2007

RINEX Version 2.12 modifications: May 2009

0.2 First Revision

The first documentation of the RINEX Version 2 Format was published by W. Gurtner and G. Mader in the CSTG GPS Bulletin of September/October 1990. The main reason for a revision is the new treatment of antispoofing data by the RINEX format (see chapter 7). Chapter 4 gives a recommendation for data compression procedures, especially useful when large amounts of data are exchanged through computer networks. In Table A3 in the original paper the definition of the "PGM / RUN BY / DATE" navigation header record was missing, although the example showed it. The redefinition of AODE/AODC to IODE/IODC also asked for an update of the format description. For consistency reasons we also defined a Version 2 format for the Meteorological Data files (inclusion of a END OF HEADER record and an optional MARKER NUMBER record).

The slight modification (or rather the definition of a bit in the Loss of Lock Indicator unused so far) to flag AS data is so small a change that we decided to NOT increase the version number!

0.3 Later Revisions

* URA Clarification (10-Dec-93):

The user range accuracy in the Navigation Message File did not contain a definition of the units: There existed two ways of interpretation: Either the 4 bit value from the original message or the converted value in meters according to GPS ICD-200. In order to simplify the interpretation for the user of the RINEX files I propose the bits to be converted into meters prior to RINEX file creation.

* GLONASS Extensions:

In March 1997 a proposal for extensions to the current RINEX definitions based on experiences collected with GLONASS only and mixed GPS/GLONASS data files was circulated among several instrument manufacturers and software developers.

The results of the call for comments have been worked into this document. A separate document (glonass.txt) summarizes just the necessary extensions.

- * A blank satellite identifier is allowed in pure GPS files only
- * Met sensor description and position records were added to facilitate the precise use of met values.
- * Description and examples for wavelength factors and their temporary changes (bit 1 of LLI) clarified.
- * The RINEX documentation distributed in spring 1997 contained definitions for the GLONASS satellite clock offset and drift with the intention to have them defined identically to the GPS values. Unfortunately the GLONASS Interface Document consulted had a sign error in one of the formulae.

The values should be stored into the RINEX file as $-\text{TauN}$, $+\text{GammaN}$, $-\text{TauC}$. The original definition asked for $-\text{TauN}$, $-\text{GammaN}$, $+\text{TauC}$. See paragraph 8.2.

To avoid problems with files created with the original definitions a real valued version number (2.01) has been introduced for GLONASS nav mess files.

- * IGS decided to use the Hatanaka compression scheme for RINEX observation files. Below the corresponding RINEX file name conventions are included as recommendations. The DOS naming (extension .yyE) was wrongly set to .yyY in the March 1998 version of the document.
- * GPS week: The GPS week number in all RINEX files is a continuous number not affected by the 1024 roll-over, it runs from 1023 over 1024 to 1025 etc.
- * A discrepancy between the definition of the header line fields of met sensor description and position in Table A5 and the example in Table A9 was removed. The latter was correct.

- * Clarification for phase data format overflows: Add or subtract a suitable number of cycles, set LLI flag.
- * Clarification for the GLONASS satellite identifier: "Almanac number" was somewhat ambiguous. It has been replaced by "slot number" within the satellite constellation.

0.4 Version 2.10 Modifications (July 1999)

The modifications leading to Version 2.10 include:

- Fractional version number
- Zero padding of 2-digit year values (years 2000–2009 --> 00–09)
- Field length of time of first obs (1/10 microsecond resolution)
- Non-integer sampling rate (INTERVAL header record)
- Header records now allowed after all epoch flags >1
- Additional obs types in obs files: S1, S2 (raw signal strength values)
- Receiver clock offset header line to clarify applied corrections
- Default wavelength factor header line mandatory
- Inmarsat GPS payloads: New satellite system definition, new nav mess files
- Curve fit interval in GPS nav mess file
- Redefinition of SV health value in GPS nav mess file
- Additional obs types in met files (ZD, ZT)

0.5 Version 2.10 Revisions

- * "Header records now allowed after all epoch flags >2" in paragraph 0.4 should read ">1"
- * The original intention of the RINEX format was to allow for variable record lengths of the ASCII files to minimize the file size. Empty fields or unknown values can either be represented by zeroes or blank space. Most RINEX converters removed trailing blank to further reduce the file size. The documentation was not clear enough to explicitly allow for this practice (paragraphs 2, 5.3, 9.1).
- * The time system identifier of GPS observations generated by GEO payloads

defaults to GPS (explicitly stated now in paragraph 9.1)

- * The time system identifier in the TIME OF LAST OBS header record has to be identical to the one in the TIME OF FIRST OBS record
- * Clarification of Table A2 to be compatible with examples of Table A7:
For event flags without significant epoch the epoch fields can be left blank.
Table A6: Format for epoch contained obvious errors
- * Clarification of the floating point exponent format in navigation message files (two digits, E, e, D, d letters)

0.6 Version 2.11 **Modifications** (October 2004)

The modifications of 2.10 leading to Version 2.11 include

- Definition of the Galileo satellite system code
- Definition of the code for Galileo System Time (GAL)
- Definition of the frequency numbers for Galileo and new GPS observables
- Observation code for L2C pseudorange (G2)
- Some clarifications in the GEO NAV Message files
 - Transmission time of message
 - Health
 - URA
 - CORR TO SYSTEM TIME replaced by more general D-UTC A0, A1, T, W, S, U record
- Introduction of wind speed and direction, rain fall increment, hail indicator
- Recommendation regarding unknown/undefined observation types and header records
- Recommendations for extended filenames for high-rate observation files

Clarifications:

- Continuation records in RINEX headers: They also have to include the respective header label in columns 61-80.
- The newer GLONASS satellites started using frequency numbers in the 0 to -7 range. Table A11 BROADCAST ORBIT - 2 was modified accordingly.

0.7 Version 2.12 Modifications (June 2009)

New features leading to Version 2.12 include

- Phase Cycle Shifts
- Galileo: BOC-Tracking of an MBOC-Modulated Signal
- New Observation Codes for GPS L1C, L2C, L1 (C/A) and Glonass G1 (SA), G2 (SA) and Compass
- System code for the Compass Satellite System
- Galileo Navigation Message File
- Unification of the TIME SYSTEM CORR record
- Unification of the IONOSPHERIC CORR record
- Order of data records

0.8 QZSS Extension Modifications

- New Observation Codes for QZSS
- System code for the QZSS Satellite System

1. THE PHILOSOPHY OF RINEX

The first proposal for the "Receiver Independent Exchange Format" RINEX has been developed by the Astronomical Institute of the University of Berne for the easy exchange of the GPS data to be collected during the large European GPS campaign EUREF 89, which involved more than 60 GPS receivers of 4 different manufacturers. The governing aspect during the development was the following fact:

Most geodetic processing software for GPS data use a well-defined set of observables:

- the carrier-phase measurement at one or both carriers (actually being a measurement on the beat frequency between the received carrier of the satellite signal and a receiver-generated reference frequency).
- the pseudorange (code) measurement, equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal.

- the observation time being the reading of the receiver clock at the instant of validity of the carrier-phase and/or the code measurements.

Usually the software assumes that the observation time is valid for both the phase AND the code measurements, AND for all satellites observed.

Consequently all these programs do not need most of the information that is usually stored by the receivers: They need phase, code, and time in the above mentioned definitions, and some station-related information like station name, antenna height, etc.

2. GENERAL FORMAT DESCRIPTION

Currently the format consists of eight ASCII file types:

1. Observation Data File
2. Navigation Message File
3. Meteorological Data File
4. GLONASS Navigation Message File
5. GEO Navigation Message File
8. Galileo Navigation Message File
7. SBAS Broadcast Data File
8. Satellite and Receiver Clock Date File

The format definition of the clock files has been published in 1998 in a separate document by Jim Ray and Werner Gurtner, available at the IGS Central Bureau Information System:

ftp://igsbc.jpl.nasa.gov/igsbc/data/format/rinex_clock.txt

The format definition of the Space-based augmentation system (SBAS) broadcast data file has been published in 2004 by Norbert Suard, Werner Gurtner and Lou Estey, available at the IGS Central Bureau Information System:

ftp://igsbc.jpl.nasa.gov/igsbc/data/format/geo_sbas.txt

All RINEX documents are available at

ftp://igsb.jpl.nasa.gov/igsb/data/format/geo_sbas.txt
ftp://ftp.unibe.ch/aiub/rinex

Each file type consists of a header section and a data section. The header section contains global information for the entire file and is placed at the beginning of the file. The header section contains header labels in columns 61–80 for each line contained in the header section. These labels are mandatory and must appear exactly as given in these descriptions and examples.

The format has been optimized for minimum space requirements independent from the number of different observation types of a specific receiver by indicating in the header the types of observations to be stored. In computer systems allowing variable record lengths the observation records may be kept as short as possible. Trailing blanks can be removed from the records. The maximum record length is 80 bytes per record.

Each Observation file and each Meteorological Data file basically contain the data from one site and one session. RINEX Version 2 also allows to include observation data from more than one site subsequently occupied by a roving receiver in rapid static or kinematic applications. Although Version 2 allows to insert header records into the data field we do not recommend to concatenate data of more than one receiver (or antenna) into the same file, even if the data do not overlap in time.

If data from more than one receiver has to be exchanged it would not be economical to include the identical satellite messages collected by the different receivers several times. Therefore the Navigation Message File from one receiver may be exchanged or a composite Navigation Message File created containing non-redundant information from several receivers in order to make the most complete file.

The format of the data records of the RINEX Version 1 Navigation Message file is identical to the former NGS exchange format.

The actual format descriptions as well as examples are given in the Tables at the end of the paper.

3. DEFINITION OF THE OBSERVABLES

GPS observables include three fundamental quantities that need to be defined: Time, Phase, and Range.

TIME:

The time of the measurement is the receiver time of the received signals. It is identical for the phase and range measurements and is identical for all satellites observed at that epoch. It is expressed in GPS time (not Universal Time).

PSEUDO-RANGE:

The pseudo-range (PR) is the distance from the receiver antenna to the satellite antenna including receiver and satellite clock offsets (and other biases, such as atmospheric delays):

$$\text{PR} = \text{distance} + c * (\text{receiver clock offset} - \text{satellite clock offset} + \text{other biases})$$

so that the pseudo-range reflects the actual behavior of the receiver and satellite clocks. The pseudo-range is stored in units of meters.

See also clarifications for pseudoranges in mixed GPS/GLONASS files in chapter 8.1.

PHASE:

The phase is the carrier-phase measured in whole cycles. The half-cycles measured by squaring-type receivers must be converted to whole cycles and flagged by the wavelength factor in the header section (GPS only).

The phase changes in the same sense as the range (negative doppler). The phase observations between epochs must be connected by including the integer number of cycles. The phase observations will not contain any systematic drifts from intentional offsets of the reference oscillators.

The observables are not corrected for external effects like atmospheric refraction, satellite clock offsets, etc.

If necessary phase observations are corrected for phase shifts needed to guarantee consistency between phases of the same frequency and satellite system based on different signal channels (see section 11.1 below).

If the receiver or the converter software adjusts the measurements using the real-time-derived receiver clock offsets $dT(r)$, the consistency of the 3 quantities phase / pseudo-range / epoch must be maintained, i.e. the receiver clock correction should be applied to all 3 observables:

$$\begin{aligned} \text{Time}(\text{corr}) &= \text{Time}(r) - dT(r) \\ \text{PR}(\text{corr}) &= \text{PR}(r) - dT(r)*c \\ \text{phase}(\text{corr}) &= \text{phase}(r) - dT(r)*\text{freq} \end{aligned}$$

DOPPLER:

The sign of the doppler shift as additional observable is defined as usual: Positive for approaching satellites.

4. THE EXCHANGE OF RINEX FILES:

We recommend using the following naming convention for RINEX files:

ssssdddf.yyt

				+--	t: file type:
					O: Observation file
					N: GPS Navigation file
					M: Meteorological data file
					G: GLONASS Navigation file
					L: Future Galileo Navigation file
					H: Geostationary GPS payload nav mess file
					B: Geo SBAS broadcast data file
					(separate documentation)
					C: Clock file (separate documentation)
					S: Summary file (used e.g., by IGS, not a standard!)
					<u>Q: QZSS Navigation file</u>

```

| | | +--- yy: two-digit year
| | |
| | +----- f: file sequence number/character within day
| |         daily file: f = 0
| |         hourly files:
| |         f = a: 1st hour 00h-01h; f = b: 2nd hour 01h-02h; ...
| |         f = x: 24th hour 23h-24h
| |
| +----- ddd: day of the year of first record
|
+----- ssss: 4-character station name designator

```

For 15-minutes high-rate tracking data we recommend the following extended filenames:

ssssdddhmm.yyo

```

| | || | |
| | || | +- o: observation file
| | || |
| | || +--- yy: two-digit year
| | ||
| | | +----- mm: starting minute within the hour (00, 15, 30, 45)
| | |
| | +----- h: character for the n-th hour in the day
| |         (a= 1st hour: 00h-01h, b= 2nd hour: 1h to 2h, ...,
| |         x=24th hour: 23h-24h. 0= one-day file)
| |
| +----- ddd: day of the year
|
+----- ssss: 4-character ID for the LEO receiver/antenna

```

When data transmission times or storage volumes are critical we recommend compressing the files prior to storage or transmission using the UNIX "compress" und "uncompress" programs. Compatible routines are available on VAX/VMS and PC/DOS systems, as well.

Proposed file name extensions for the compressed files:

File Types	All platforms uncompressed	UNIX compressed	VMS compressed	DOS
Obs Files	.yy0	.yy0.Z	.yy0_Z	.yyY
Obs Files (Hatanaka compressed)	.yyD	.yyD.Z	.yyD_Z	.yyE
GPS Nav Files	.yyN	.yyN.Z	.yyN_Z	.yyX
GLONASS Nav File	.yyG	.yyG.Z	.yyG_Z	.yyV
Galileo Nav File	.yyL	.yyL.Z	.yyL_Z	.yyT
GEO Nav Files	.yyH	.yyH.Z	.yyH_Z	.yyU
GEO SBAS Broadcast Files (sep. doc.)	.yyB	.yyB.Z	.yyB_Z	.yyA
Met Data Files	.yyM	.yyM.Z	.yyM_Z	.yyW
Clock Files (see sep.doc.)	.yyC	.yyC.Z	.yyC_Z	.yyK
QZSS Nav Message File	.yyQ	.yyQ.Z	.yyQ_Z	.yyJ

References for the Hatanaka compression scheme: See e. g.

- ftp://terras.gsi.go.jp/software/RNXCMP
- IGSMails 1525, 1686, 1726, 1763, 1785, 4967, 4969, 4975, 5609, 5611

5. RINEX VERSION 2 FEATURES

The following section contains features that have been introduced for RINEX Version 2:

5.1 Satellite Numbers:

Version 2 has been prepared to contain GLONASS or other satellite systems' observations. Therefore we have to be able to distinguish the satellites of the different systems: We precede the 2-digit satellite number with a system identifier.

snn	s:	satellite system identifier
		G or blank : GPS
		R : GLONASS
		S : Geostationary signal payload
		E : Galileo
		C : Compass

- J : QZSS
- nn: – PRN (GPS, Galileo, Compass)
 – slot number (GLONASS)
 – PRN-100 (GEO)
 – PRN-192 (QZSS)

Note: G is mandatory in mixed GPS/GLONASS/Galileo files

PRN number runs from 193 to 202 for QZSS other observation signals. In order to treat this PRN condition, QZSS use “PRN-192 rule” .

(blank default modified in April 1997)

5.2 Order of the Header Records:

As the record descriptors in columns 61–80 are mandatory, the programs reading a RINEX Version 2 header are able to decode the header records with formats according to the record descriptor, provided the records have been first read into an internal buffer.

We therefore propose to allow free ordering of the header records, with the following exceptions:

- The “RINEX VERSION / TYPE” record must be the first record in a file
- The default “WAVELENGTH FACT L1/2” record must precede all records defining wavelength factors for individual satellites
- The “# OF SATELLITES” record (if present) should be immediately followed by the corresponding number of “PRN / # OF OBS” records. (These records may be handy for documentary purposes. However, since they may only be created after having read the whole raw data file we define them to be optional.

5.3 Missing Items, Duration of the Validity of Values

Items that are not known at the file creation time can be set to zero or blank or the respective record may be completely omitted. Consequently items of missing header records will be set to zero or blank by the program reading RINEX files. Trailing blanks may be truncated from the record.

Each value remains valid until changed by an additional header record.

5.4 Event Flag Records

The “number of satellites” also corresponds to the number of records of the same epoch followed. Therefore it may be used to skip the appropriate number of records if certain event flags are not to be evaluated in detail.

5.5 Receiver Clock Offset

A large number of users asked to optionally include a receiver-derived clock offset into the RINEX format. In order to remove uncertainties if the data (epoch, pseudorange, phase) have been previously corrected or not by the reported clock offset, RINEX Version 2.10 requests a clarifying (new) header record.

It would then be possible to reconstruct the original observations if necessary.

As the output format for the receiver-derived clock offset is limited to nanoseconds the offset should be rounded to the nearest nanosecond before it is used to correct the observables in order to guarantee correct reconstruction.

6. ADDITIONAL HINTS AND TIPS

6.1 Versions

Programs developed to read RINEX files have to verify the version number. Files of newer versions may look different even if they do not use any of the newer features

6.2 Leading Blanks in CHARACTER fields

We propose that routines to read RINEX Version 2 files automatically delete leading blanks in any CHARACTER input field. Routines creating RINEX Version 2 files should also left-justify all variables in the CHARACTER fields.

6.3 Variable-length Records

DOS, and other, files may have variable record lengths, so we recommend to first read each observation record into a 80-character blank string and decode the data afterwards. In variable length records, empty data fields at the end of a record may be missing, especially in the case of the optional receiver clock offset.

6.4 Blank Fields

In view of future modifications we recommend to carefully skip any fields currently defined to be blank (Format fields nX), because they may be assigned to new contents in future versions.

6.5 2-Digit Years

RINEX version 2 stores the years of data records with two digits only. The header of observation files contains a TIME OF FIRST OBS record with the full four-digit year, the GPS nav messages contain the GPS week numbers. From these two data items the unambiguous year can easily be reconstructed.

A hundred-year ambiguity occurs in the met data and GLONASS and GEO nav messages: Instead of introducing a new TIME OF FIRST OBS header line it is safe to stipulate that any two-digit years in RINEX Version 1 and Version 2.xx files are understood to represent

80-99: 1980-1999

00-79: 2000-2079

Full 4-digit year fields could then be defined by a future RINEX version 3.

6.6 Fit Interval

Bit 17 in word 10 of subframe 2 is a "fit interval" flag which indicates the curve-fit interval used by the GPS Control Segment in determining the ephemeris parameters, as follows (see ICD-GPS-200, 20.3.3.4.3.1):

0 = 4 hours

1 = greater than 4 hours.

Together with the IODC values and Table 20–XII the actual fit interval can be determined. The second value in the last record of each message shall contain the fit interval in hours determined using IODC, fit flag, and Table 20–XII, according to the Interface Document ICD–GPS–200.

6.7 Satellite Health

The health of the signal components (bits 18 to 22 of word three in subframe one) are now (Version 2.10) included into the health value reported in the second field of the sixth nav mess records.

A program reading RINEX files could easily decide if bit 17 only or all bits (17–22) have been written:

RINEX Value: 0 Health OK
RINEX Value: 1 Health not OK (bits 18–22 not stored)
RINEX Value: >32 Health not OK (bits 18–22 stored)

6.8 Transmission Time of Message (Navigation message file)

The transmission time of message can be shortly before midnight Saturday/Sunday, the TOE and TOC of the message already in the next week. As the reported week in the RINEX nav message (BROADCAST ORBIT – 5 record) goes with ToE (this is different from the GPS week in the original satellite message!), the transmission time of message should be reduced by 604800 (i.e., will become negative) to also refer to the same week.

6.9 Unknown / Undefined Observation Types and Header Records

It is a good practice for a program reading RINEX files to make sure that it does not crash if it encounters unknown observation types or header records by properly skipping them and optionally reporting them to the user.

6.10 Order of data records

Multiple epoch data records with identical time tags are not allowed (exception: Event records).

Epochs have to appear ordered in time.

7. RINEX UNDER ANTISPOOFING (AS)

Some receivers generate code delay differences between the first and second frequency using cross-correlation techniques when AS is on and may recover the phase observations on L2 in full cycles. Using the C/A code delay on L1 and the observed difference it is possible to generate a code delay observation for the second frequency.

Other receivers recover P code observations by breaking down the Y code into P and W code.

Most of these observations may suffer from an increased noise level. In order to enable the postprocessing programs to take special actions, such AS-infected observations are flagged using bit number 2 of the Loss of Lock Indicators (i.e. their current values are increased by 4).

8. GLONASS Extensions

8.1 RINEX Observation File

8.1.1 Time System Identifier

The original RINEX Version 2 needed one major supplement, the explicit definition of the time system:

GLONASS is basically running on UTC (or, more precisely, GLONASS system time linked to UTC(SU)), i.e. the time tags are given in UTC and not GPS time. In order to remove possible misunderstandings and ambiguities, the header records "TIME OF FIRST OBS" and (if present) "TIME OF LAST OBS" in GLONASS and GPS observation files `_can_`, in mixed GLONASS/GPS observation files `_must_` contain a time system identifier defining the system that all time tags in the file are referring to: "GPS" to identify GPS time, "GLO" to identify the GLONASS UTC time system. Pure GPS files default to GPS and pure GLONASS files default to GLO.

Format definitions see Table A1.

Hence, the two possible time tags differ by the current number of leap seconds.

In order to have the current number of leap seconds available we recommend to include a LEAP SECOND line into the RINEX header.

If there are known non-integer biases between the "GPS receiver clock" and "GLONASS receiver clock" in the same receiver, they should be applied. In this case the respective code and phase observations have to be corrected, too ($c * \text{bias}$ if expressed in meters).

Unknown such biases will have to be solved for during the post processing

The small differences (modulo 1 second) between GLONASS system time, UTC(SU), UTC(USNO) and GPS system time have to be dealt with during the post-processing and not before the RINEX conversion. It may also be necessary to solve for remaining differences during the post-processing.

8.1.2 Pseudorange Definition

The pseudorange (code) measurement is defined to be equivalent to the difference of the time of reception (expressed in the time frame of the receiver) and the time of transmission (expressed in the time frame of the satellite) of a distinct satellite signal.

If a mixed-mode GPS/GLONASS receiver refers all pseudorange observations to one receiver clock only,

- the raw GLONASS pseudoranges will show the current number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GPS time frame
- the raw GPS pseudoranges will show the negative number of leap seconds between GPS time and GLONASS time if the receiver clock is running in the GLONASS time frame

In order to avoid misunderstandings and to keep the code observations within the format fields, the pseudoranges must be corrected in this case as follows:

$$\text{PR(GPS)} := \text{PR(GPS)} + c * \text{leap_seconds} \quad \text{if generated with a receiver clock running in the GLONASS time frame}$$

$PR(GLO) := PR(GLO) - c * leap_seconds$ if generated with a receiver clock running in the GPS time frame

to remove the contributions of the leap seconds from the pseudoranges.

“leap_seconds” is the actual number of leap seconds between GPS and GLONASS (UTC) time, as broadcast in the GPS almanac and distributed in Circular T of BIPM.

8.1.3 More Than 12 Satellites per Epoch

The format of the epoch / satellite line in the observation record part of the RINEX Observation files has only been defined for up to 12 satellites per epoch. We explicitly define now the format of the continuation lines, see Table A2.

8.2 RINEX Navigation Files for GLONASS

As the GLONASS navigation message differs in contents from the GPS message too much, a special GLONASS navigation message file format has been defined.

The header section and the first data record (epoch, satellite clock information) is similar to the GPS navigation file. The following records contain the satellite position, velocity and acceleration, the clock and frequency biases as well as auxiliary information as health, satellite frequency (channel), age of the information.

The corrections of the satellite time to UTC are as follows:

GPS : $T_{utc} = T_{sv} - af_0 - af_1 * (T_{sv} - T_{oc}) - \dots - A_0 - \dots - leap_sec$
GLONASS: $T_{utc} = T_{sv} + TauN - GammaN * (T_{sv} - T_b) + TauC$

*** In order to use the same sign conventions for the GLONASS corrections as in the GPS navigation files, the broadcast GLONASS values are stored as:

$-TauN, +GammaN, -TauC.$

The time tags in the GLONASS navigation files are given in UTC (i.e. `_not_`

Moscow time or GPS time).

File naming convention: See above.

9. RINEX Extensions for Geostationary Satellites (GPS Signal Payloads)

With the implementation of GNSS programs, GPS-like ranging measurements can be performed on geostationary navigation payloads.

RINEX Version 2.10 defines the necessary extensions to handle such data in RINEX files for data exchange and postprocessing purposes.

9.1 RINEX Observation Files for GEO Satellites

A new satellite system identifier has been defined for the geostationary GPS signal payloads: "S", to be used in the RINEX VERSION / TYPE header line and in the satellite identifier 'snn', nn being the GEO PRN number minus 100.

e. g. : PRN = 120 --> 'snn' = "S20"

In mixed dual frequency GPS satellite / single frequency GEO payload observation files the fields for the second frequency observations of GEO satellites remain blank, are set to zero values or (if last in the record) can be truncated.

The time system identifier of GEO satellites generating GPS signals defaults to GPS time.

9.2 RINEX Navigation Message Files for GEO Satellites

As the GEO broadcast orbit format differs from the GPS message a special GEO navigation message file format has been defined which is nearly identical with the GLONASS nav mess file format.

The header section contains informations about the generating program, comments, and the difference between the GEO system time and UTC.

The first data record contains the epoch and satellite clock information, the following records contain the satellite position, velocity and acceleration and auxiliary information such as health, age of the data, etc.

The time tags in the GEO navigation files are given in the GPS time frame, i.e. not UTC.

The corrections of the satellite time to UTC are as follows:

$$\text{GEO} \quad : \quad \text{Tutc} = \text{Tsv} - \text{aGf0} - \text{aGf1} * (\text{Tsv} - \text{Toe}) - \text{W0} - \text{leap_sec}$$

W0 being the correction to transform the GEO system time to UTC. Toe, aGf0, aGf1 see below in the format definition tables.

The "Transmission Time of Message" (PRN / EPOCH / SV CLK header record) is expressed in GPS seconds of the week. It marks the beginning of the message transmission. It has to refer to the same GPS week as the "Epoch of Ephemerides". It has to be adjusted by - or + 604800 seconds, if necessary (which would make it lower than zero or larger than 604800, respectively). It is a redefinition of the Version 2.10 "Message frame time".

"Health" shall be defined as follows:

- Bits 0 to 3 equal to Health in Message Type 17 (MT17)
- bit 4 is set to 1 if MT17 health is unavailable
- bit 5 is set to 1 if the URA index is equal to 15

In the SBAS message definitions bit 3 of the health is currently marked as 'reserved'.

In case of bit 4 set to 1, it is recommended to set bits 0,1,2,3 to 1, too.

"User Range Accuracy" (URA):

The same convention for converting the URA index to meters is used as with GPS. Set URA = 32767 meters if URA index = 15.

"IODN" (Issue Of Data Navigation)

The IODN is defined as the 8 first bits after the message type 9, called IODN in RTCA D0229, Annex A and Annex B and called "spare" in Annex C.

The "CORR TO SYSTEM" TIME header record has been replaced by the more general

record "D-UTC A0,A1,T,W,S,U" in Version 2.11 and again by the unified TIME SYSTEM CORR record of Version 2.12.

10. Version 2.11 Modifications

The main driver for version 2.11 was the easy inclusion of Galileo and new GPS observables into the RINEX format. As these modifications are VERY MINOR (no changes in the actual formats) many RINEX readers will not have to be modified at all or to a small amount (accept version number 2.11), only.

After the first introduction of the "GEO navigation message file" in Version 2.10 feedback from the SBAS community lead to a number of clarifications/redefinitions that were included in the Version 2.11 modifications.

10.1 Galileo and New GPS Observables

10.1.1 New Observation Codes

In Version 2.10 only the observation codes for two frequencies were define (Table A1).

The new codes for GPS L2C/L5 and Galileo codes are introduced as follows:

System	Freq. Band	Frequency	RINEX 2-character Code			
			Ps. Range	Carr. Phase	Doppler	Sign. Strength
GPS	L1	1575.42	C1, P1	L1	D1	S1
	L2	1227.60	C2, P2	L2	D2	S2
	L5	1176.45	C5	L5	D5	S5
Glonass	G1	1602+k*9/16	C1, P1	L1	D1	S1
	G2	1246+k*7/16	C2, P2	L2	D2	S2
Galileo	E2-L1-E1	1575.42	C1	L1	D1	S1
	E5a	1176.45	C5	L5	D5	S5
	E5b	1207.140	C7	L7	D7	S7
	E5a+b	1191.795	C8	L8	D8	S8
	E6	1278.75	C6	L6	D6	S6

SBAS	L1	1575.42	C1	L1	D1	S1	
	L5	1176.45	C5	L5	D5	S5	

The current two-character observation code does not easily allow a further refinement of the code to account for the different possibilities how to generate a specific observable, e.g., with respect to the underlying code (P,Y,M code in GPS) or the channels (I,Q, A,B,C in Galileo, I,Q in the new GPS L5 frequency, GPS L2C). The next RINEX version (3.0) will increase the length of the observation codes to allow a more detailed definition.

The definition of observations for Transit Doppler is obsolete and has been removed from Version 2.11

10.1.2 Wavelength Factors

The WAVELENGTH FACT L1/2 header record defining the factor, the carrier wavelength has to be divided with for ambiguity resolution, has been introduced because of receivers generating GPS phase observations under antispoofing with one cycle corresponding to half the carrier wavelength only (squaring technique). Galileo observables will not be generated by squaring. We therefore define the WAVELENGTH FACT L1/2 header record to be valid for L1 and L2 GPS phase observables only. All wavelength factors default to 1. This header record can therefore be declared to be optional.

10.1.3 Code for Galileo Satellite System

Use "E" to indicate the Galileo Satellite System in the header of RINEX observation files.

10.1.4 Galileo System Time

Include GAL as Galileo System Time into TIME OF FIRST OBS and TIME OF LAST OBS header records.

10.2 Clarifications in the GEO Navigation Message File

The following clarifications/modifications were introduced (see chapter 9.2):

- Health word

- Issue of Data (Navigation) IODN
- Correction to system time
- Transmission time of message

10.3 New observables for RINEX met files

Wind speed (ms), wind direction (from where the wind blows), and an incremental rain fall value (1/10 mm): rain accumulation since the last recording, hail indicator

11. Version 2.12 Modifications

11.1 Phase Cycle Shifts

Carrier phases tracked on different signal channels or modulation bands of the same frequency may differ in phase by 1/4 (e.g., GPS: P/Y code-derived L2 phase vs. L2C-based phase) or, in some exceptional cases, by other fractional parts of a cycle.

In order to facilitate data processing, phases stored in the RINEX files have to be consistent across all satellites of a satellite system and a specific frequency within the current RINEX file with respect to such cycle shifts:

Either one or the other group of phase observations have to be shifted by the respective fraction of a cycle, either directly by the receiver or by a correction program or the RINEX conversion program prior to RINEX file generation, to align them to each other.

The applied corrections are to be reported in a new SYS / PHASE SHIFT header record to allow the reconstruction of the original values, if needed. The uncorrected group of observations is not reported in the SYS / PHASE SHIFT records.

In case the reported phase correction of an observation type does not affect all satellites of the same system, the header record allows to also indicate a list of the respective satellites.

The SYS / PHASE SHIFT header record is mandatory. If the file does not contain any observation pairs affected by phase shifts or if (exceptionally) the applied corrections are not known, the observation code field and the rest of the SYS / PHASE SHIFT header record field of the respective satellite system(s)

are left blank.

Sign of the correction delta phase:

$$\text{phase(RINEX)} = \text{phase(original)} + \text{delta phase}$$

phase(original): Uncorrected, i.e. as sent by the satellite

delta phase : Phase correction to align the phase to other phases of the same frequency but different channel / modulation band

11.2 Galileo: BOC-Tracking of an MBOC-Modulated Signal

Galileo L1 will be modulated by the so-called MBOC modulation. Obviously it is possible for a receiver to track the signal also in a BOC mode, leading to different noise characteristics, though. In order to keep this non-standard tracking mode of a MBOC signal apart, bit 2 of the loss-of-lock indicator (the anti-spoofing flag not used for Galileo) in the observation data records is used.

Non-standard BOC tracking of an MBOC-modulated signal: Increase the LLI by 4.

11.3 New Observation Codes for GPS L1C, L2C, L1(C/A), Glonass G1(SA), G2(SA), and Compass

System	Freq Code		Frequency	RINEX 2-Character Codes			
	Channel			Ps. Range	Carr. Phase	Doppler	Sign. Strength
GPS	L1	P, Y	1575.42	P1	L1	D1	S1
	L1	C/A	1575.42	CA	LA	DA	SA
	L1	L1C	1575.42	CB	LB	DB	SB
	L2	P, Y	1227.60	G2, P2	L2	D2	S2
	L2	L2C	1227.60	CC	LC	DC	SC
Glonass	G1	HA	$1602+k*9/16$	P1	L1	D1	S1
	G1	SA	$1602+k*9/16$	CA	LA	DA	SA
	G2	HA	$1246+k*7/16$	P2	L2	D2	S2
	G2	SA	$1246+k*7/16$	CD	LD	DD	SD

Compass	E2	I/Q	G2	L2	D2	S2
	E5b	I/Q	G7	L7	D7	S7
	E6	I/Q	G6	L6	D6	S6

GPS C2: CA+(P2-P1) Pseudorange based on C/A(L1) and difference P2-P1 or Y2-Y1

Glonass SA: Based on standard accuracy code
 HA: Based on high accuracy code

11.4 Compass Satellite System Code

Satellite system code for Compass: 'C'

11.5 Galileo Navigation Message File

The definitions for Galileo Navigation Message files are taken from RINEX Version 3.01. See Tables A19, A20.

11.6 Unification of the TIME SYSTEM CORR record

The three different RINEX navigation message file header records

- GPS: DELTA-UTC: A0, A1, T, W
- SBAS: D-UTC A0, A1, T, W, S, U
- GLONASS: CORR TO SYSTEM TIME

are replaced by one unique TIME SYSTEM CORR record, also used for Galileo nav mess files. See Tables A3, A10, A15, and A19.

11.7 Unification of the IONOSPHERIC CORR record

The ION ALPHA and ION BETA header records of the GPS navigation message file are replaced by the IONOSPHERIC CORR record, which is also used for Galileo navigation message files. See Tables A3 and A19.

11.8 Order of data records

Multiple epoch data records with identical time tags are not allowed (exception: Event records).

Epochs have to appear ordered in time.

11.9 RINEX Meteorological Data Files

The version number is adjusted to 2.12.

12. Modifications for QZSS

As these modifications are VERY MINOR (no changes in the actual formats) many RINEX readers will not have to be modified at all or to a small amount, only.

12.1 QZSS signals

12.1.1 Signal configuration of L1 signals

QZS transmits two signals using the L1 center frequency: the L1C/A signal and the L1C signal.

12.1.2 L2C signal configuration

The L2C signal has a single carrier wave. This carrier wave is BPSK modulated using a certain bit string. This bit string is generated by two types of bit strings (corresponding to two channels) that are selected alternately in a time-multiplexed manner.

12.1.3 L5 signal configuration

The L5 signal has two carrier waves that are orthogonal with respect to one another. Each of these carrier waves is BPSK modulated by two types of bit strings (corresponding to the two channels).

12.1.4 LEX signal configuration

The LEX is L-Band Experimental Signal. Its Frequency is 1278.75MHz (same as Galileo E6)

The LEX signal has a single carrier wave. This carrier wave is BPSK modulated by a certain bit string. This bit string is generated by two types of bit strings (corresponding to two channels) that are selected alternately in a time-multiplexed manner.

12.2 New Observation Codes for QZSS

System	Freq Code		Frequency	RINEX 2-Character Codes			
	Channel			Ps. Range	Carr. Phase	Doppler	Sign. Strength
QZSS	L1	C/A	1575.42	CA	LA	DA	SA
	L1	L1C	1575.42	CB	LB	DB	SB
	L2	L2C	1227.60	CC	LC	DC	SC
	L5	I/Q	1176.45	C5	L5	D5	S5
	LEX	S/L	1278.75	C6	L6	D6	S6

12.3 PRN Code Numbers for QZSS

12.3.1 Availability Enhancement Signals

QZSS uses the same type of PRN code as GPS. The PRN code numbers used by QZSS are 193–202. The initial QZS is assigned code number 193, and the second and succeeding QZS are assigned numbers in sequence starting with 194.

12.3.2 Performance Enhancement Signals

(1) LEX Signal

A small Kasami series is used. The numbers are 193–202. The initial QZS is assigned number 193, and the second and succeeding QZS are assigned numbers in sequence starting with 194.

12.4 QZSS Satellite System Code

Satellite system code for QZSS: 'J'

12.5 QZSS Navigation Message File

QZSS superimposes onto the PRN code data to aid identification of QZS position as well as other data described in the following subsections. As is typical of other GNSS systems, QZS transmits this information in the form of navigation messages.

12.6 Time system on QZSS

QZSS runs on QZSST, which has the following characteristics. QZSST conforms to UTC (NICT) and the offset with respect to the GPS time system is controlled.

- One second length
The length of one second is identical to International Atomic Time (TAI). It is also the same for GPS and Galileo.
- Integer second offset for TAI

The integer second offset for TAI is the same as for GPS. TAI is always 19 seconds ahead of QZSST.

- Starting point of Week Number for QZSST

The starting point of the Week Number for QZST is identical to GPST.

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Document RTCA DO 229, Appendix A

APPENDIX: RINEX VERSION 2.11 FORMAT DEFINITIONS AND EXAMPLES

TABLE A1			
GNSS OBSERVATION DATA FILE – HEADER SECTION DESCRIPTION			
HEADER LABEL (Columns 61–80)	DESCRIPTION	FORMAT	
RINEX VERSION / TYPE	- Format version (2.12)	F9.2,11X,	
	- File type ('O' for Observation Data)	A1,19X,	
	- Satellite System: blank or 'G': GPS	A1,19X	
	'R': GLONASS		
	'S': Geostationary signal payload		
	'E': Galileo		
	'M': Mixed		
	<u>'J': QZSS</u>		
PGM / RUN BY / DATE	- Name of program creating current file	A20,	
	- Name of agency creating current file	A20,	
	- Date of file creation	A20	
* COMMENT	Comment line(s)	A60	*
MARKER NAME	Name of antenna marker	A60	
* MARKER NUMBER	Number of antenna marker	A20	*
OBSERVER / AGENCY	Name of observer / agency	A20, A40	
REC # / TYPE / VERS	Receiver number, type, and version	3A20	
	(Version: e.g. Internal Software Version)		
ANT # / TYPE	Antenna number and type	2A20	
APPROX POSITION XYZ	Approximate marker position (WGS84)	3F14.4	

ANTENNA: DELTA H/E/N	- Antenna height: Height of bottom surface of antenna above marker - Eccentricities of antenna center relative to marker to the east and north (all units in meters)	3F14.4	
* WAVELENGTH FACT L1/2	- Default wavelength factors for L1 and L2 (GPS only) 1: Full cycle ambiguities 2: Half cycle ambiguities (squaring) 0 (in L2): Single frequency instrument - zero or blank The wavelength factor record is optional for GPS and obsolete for other systems. Wavelength factors default to 1. If the record exists it must precede any satellite-specific records (see below).	2I6, I6	*
* WAVELENGTH FACT L1/2	- Wavelength factors for L1 and L2 (GPS) 1: Full cycle ambiguities 2: Half cycle ambiguities (squaring) 0 (in L2): Single frequency instrument - Number of satellites to follow in list for which these factors are valid. - List of PRNs (satellite numbers with system identifier) These optional satellite specific lines may follow, if they identify a state different from the default values. Repeat record if necessary.	2I6, I6, 7(3X, A1, I2)	*
# / TYPES OF OBSERV	- Number of different observation types stored in the file - Observation types - Observation code - Frequency code	I6, 9(4X, A1, A1)	

If more than 9 observation types:

Use continuation line(s) (including the header label in cols. 61–80!) | 6X, 9 (4X, 2A1)

The following observation types are defined in RINEX Version 2.12:

Observation code (use uppercase only):

C: Pseudorange GPS: C/A, L2C
 Glonass: C/A (SA)
 Galileo: All
QZSS: C/A, L1C, L2C, L5, LEX

P: Pseudorange GPS: P code
 Glonass: P code (HA)

L: Carrier phase

D: Doppler frequency

S: Raw signal strengths or SNR values as given by the receiver for the respective phase observations

Frequency code:

	GPS	Glonass	Galileo	SBAS	Compass	QZSS
1: L1 (P, Y)	L1 (HA)	E2–L1–E1	L1	E1		
A: L1 (C/A)	L1 (SA)	--	--			L1 (C/A)
B: L1 (L1C)	--	--	--			L1 (L1C)
2: L2 (P, Y)	L2 (HA)	--	--	E2		
C: L2 (L2C)	--	--	--			L2 (L2C)
D: --	L2 (SA)	--	--			
5: L5	--	E5a	L5			L5
6: --	--	E6	--	E6		LEX
7: --	--	E5b	--	E5b		
8: --	--	E5a+b	--			

1: L1 (P, Y)	L1 (HA)	E2–L1–E1	L1	E1	
--------------	---------	----------	----	----	--

A: L1 (C/A)	L1 (SA)	--	--		L1 (C/A)
-------------	---------	----	----	--	----------

B: L1 (L1C)	--	--	--		L1 (L1C)
-------------	----	----	----	--	----------

2: L2 (P, Y)	L2 (HA)	--	--	E2	
--------------	---------	----	----	----	--

C: L2 (L2C)	--	--	--		L2 (L2C)
-------------	----	----	----	--	----------

D: --	L2 (SA)	--	--		
-------	---------	----	----	--	--

5: L5	--	E5a	L5		L5
-------	----	-----	----	--	----

6: --	--	E6	--	E6	LEX
-------	----	----	----	----	-----

7: --	--	E5b	--	E5b	
-------	----	-----	----	-----	--

8: --	--	E5a+b	--		
-------	----	-------	----	--	--

SA: Based on standard accuracy code.

HA: Based on high accuracy code.

Observations collected under Antispoofing are converted to "L2" or "P2" and flagged with bit 2 of loss of lock indicator (see Table A2).

	Units : Phase : full cycles		
	Pseudorange : meters		
	Doppler : Hz		
	SNR etc : receiver-dependent		
	The sequence of the types in this record has to correspond to the sequence of the observations in the observation records		
* INTERVAL	Observation interval in seconds	F10.3	*
TIME OF FIRST OBS	- Time of first observation record (4-digit-year, month, day, hour, min, sec)	5I6, F13.7,	
	- Time system: GPS (=GPS time system)	5X, A3	
	GLO (=UTC time system)		
	GAL (=Galileo System Time)		
	<u>QZS (=QZSS System Time)</u>		
	Compulsory in mixed GPS/GLONASS files		
	Defaults: GPS for pure GPS files		
	GLO for pure GLONASS files		
	GAL for pure Galileo files		
* TIME OF LAST OBS	- Time of last observation record (4-digit-year, month, day, hour, min, sec)	5I6, F13.7,	*
	- Time system: Same value as in TIME OF FIRST OBS record	5X, A3	
* RCV CLOCK OFFS APPL	Epoch, code, and phase are corrected by applying the realtime-derived receiver clock offset: 1=yes, 0=no; default: 0=no	16	*
	Record required if clock offsets are reported in the EPOCH/SAT records		
* LEAP SECONDS	Number of leap seconds since 6-Jan-1980	16	*
	Recommended for mixed files		
SYS / PHASE SHIFT	Phase shift correction used to generate phases consistent w/r to cycle shifts		
	- Satellite system (G/R/E/S/C/J)	A1, 1X,	

	- Carrier phase observation code	A2, 2X,	
	- Type		
	- Band		
	- Correction applied (cycles)	F8.5	
	- Number of satellites involved	2X, I2.2,	
	0 or blank: All satellites of system		
	- List of satellites	10 (1X, A3)	
	Use continuation line(s) for more than 10 satellites.	18X, 10 (1X, A3)	
	Repeat the record for all affected codes.		
	Leave observation code and rest of the field blank if applied corrections for the respective satellite system are unknown.		
	See paragraph 11.1		

* # OF SATELLITES	Number of satellites, for which observations are stored in the file	I6	*

* PRN / # OF OBS	PRN (sat.number), number of observations for each observation type indicated in the "# / TYPES OF OBSERV" - record.	3X, A1, I2, 9I6	*
	If more than 9 observation types: Use continuation line(s) including the header label in cols. 61-80!	6X, 9I6	
	In order to avoid format overflows, 99999 indicates >= 99999 observations in the RINEX file.		
	This record is (these records are) repeated for each satellite present in the data file		

END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A2		
GNSS OBSERVATION DATA FILE – DATA RECORD DESCRIPTION		
OBS. RECORD	DESCRIPTION	FORMAT
EPOCH/SAT	- Epoch :	
or	- year (2 digits, padded with 0 if necessary)	1X, I2.2,
EVENT FLAG	- month, day, hour, min,	4(1X, I2),
	- sec	F11.7,
	- Epoch flag 0: OK	2X, I1,
	1: power failure between	
	previous and current epoch	
	>1: Event flag	
	- Number of satellites in current epoch	I3,
	- List of PRNs (sat. numbers with system	12(A1, I2),
	identifier, see 5.1) in current epoch	
	- receiver clock offset (seconds, optional)	F12.9
	If more than 12 satellites: Use continuation	32X,
	line(s)	12(A1, I2)
	If epoch flag 2-5:	
	- Event flag:	[2X, I1,]
	2: start moving antenna	
	3: new site occupation (end of kinem. data)	
	(at least MARKER NAME record follows)	
	4: header information follows	
	5: external event (epoch is significant,	
	same time frame as observation time tags)	
	- "Number of satellites" contains number of	[I3]
	special records to follow.	

	Maximum number of records: 999		
	- For events without significant epoch the epoch fields can be left blank		
	If epoch flag = 6:		
	6: cycle slip records follow to optionally report detected and repaired cycle slips (same format as OBSERVATIONS records; slip instead of observation; LLI and signal strength blank or zero)		
<hr/>			
OBSERVATIONS	- Observation	rep. within record for	m(F14.3,
	- LLI	each obs.type (same seq	I1,
	- Signal strength	as given in header)	I1)
	If more than 5 observation types (=80 char): continue observations in next record.		
	This record is (these records are) repeated for each satellite given in EPOCH/SAT - record.		
	Observations:		
	Phase	: Units in whole cycles of carrier	
	Code	: Units in meters	
	Missing observations are written as 0.0 or blanks.		
	Phase values overflowing the fixed format F14.3 have to be clipped into the valid interval (e.g. add or subtract 10**9), set LLI indicator.		
	Loss of lock indicator (LLI). Range: 0-7		
	0 or blank: OK or not known		
	Bit 0 set	: Lost lock between previous and current observation: cycle slip possible	
	Bit 1 set	: Opposite wavelength factor to the one defined for the satellite by a previous WAVELENGTH FACT L1/2 line	

	or opposite to the default.	
	Valid for the current epoch only.	
Bit 2 set :	GPS: Observation under antispoofing (may suffer from increased noise).	
	Galileo: BOC-tracking of an MBOC- modulated signal (may suffer from increased noise).	
	Bits 0 and 1 for phase only.	
	Signal strength projected into interval 1-9:	
	1: minimum possible signal strength	
	5: threshold for good S/N ratio	
	9: maximum possible signal strength	
	0 or blank: not known, don't care	

TABLE A3
GPS NAVIGATION MESSAGE FILE – HEADER SECTION DESCRIPTION

HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT
RINEX VERSION / TYPE	- Format version (2.12) - File type ('N' for Navigation data)	F9.2, 11X, A1, 19X
PGM / RUN BY / DATE	- Name of program creating current file - Name of agency creating current file - Date of file creation	A20, A20, A20
* COMMENT	Comment line(s)	A60
* IONOSPHERIC CORR	Ionospheric correction parameters - Correction type GPSA = GPS alpha0 - alpha3 GPSB = GPS beta0 - beta3 - Parameters GPS: alpha0-alpha3 or beta0-beta3	A4, 1X, 4D12.4

* ION ALPHA	Ionosphere parameters A0–A3 of almanac (page 18 of subframe 4)	2X, 4D12. 4	*
* ION BETA	Ionosphere parameters B0–B3 of almanac	2X, 4D12. 4	*
* TIME SYSTEM CORR	Corrections to transform the system time to UTC - Correction type GPUT = GPS to UTC a0, a1 - a0, a1 Coefficients of 1-deg polynomial (a0 sec, a1 sec/sec) CORR(s) = a0 + a1*DELTAT - T Reference time for polynomial (Seconds into GPS week) - W Reference week number (GPS week, continuous number)	A4, 1X, D17. 10, D16. 9, 17, 15, 10X	*
* LEAP SECONDS	Delta time due to leap seconds	16	*
END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A4		
GPS NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION		
OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite PRN number	12,
	- Epoch: Toc – Time of Clock	
	year (2 digits, padded with 0	
	if necessary)	1X, 12. 2,
	month	1X, 12,
	day	1X, 12,
	hour	1X, 12,
	minute	1X, 12,

	second	F5.1,
	- SV clock bias (seconds)	3D19.12
	- SV clock drift (sec/sec)	
	- SV clock drift rate (sec/sec ²)	*)

BROADCAST ORBIT - 1	- IODE Issue of Data, Ephemeris	3X, 4D19.12
	- Crs (meters)	
	- Delta n (radians/sec)	
	- MO (radians)	

BROADCAST ORBIT - 2	- Cuc (radians)	3X, 4D19.12
	- e Eccentricity	
	- Cus (radians)	
	- sqrt(A) (sqrt(m))	

BROADCAST ORBIT - 3	- Toe Time of Ephemeris	3X, 4D19.12
	(sec of GPS week)	
	- Cic (radians)	
	- OMEGA (radians)	
	- CIS (radians)	

BROADCAST ORBIT - 4	- i0 (radians)	3X, 4D19.12
	- Crs (meters)	
	- omega (radians)	
	- OMEGA DOT (radians/sec)	

BROADCAST ORBIT - 5	- IDOT (radians/sec)	3X, 4D19.12
	- Codes on L2 channel	
	- GPS Week # (to go with TOE)	
	Continuous number, not mod(1024)!	
	- L2 P data flag	

BROADCAST ORBIT - 6	- SV accuracy (meters)	3X, 4D19.12
	- SV health (bits 17-22 w 3 sf 1)	
	- TGD (seconds)	
	- IODC Issue of Data, Clock	

BROADCAST ORBIT - 7	- Transmission time of message (**)	3X, 4D19.12
	(sec of GPS week, derived e.g.	
	from Z-count in Hand Over Word (HOW)	

	- Fit interval (hours)	
	(see ICD-GPS-200, 20.3.4.4)	
	Zero if not known	
	- spare	
	- spare	

***) Adjust the Transmission time of message by -604800 to refer to the reported week, if necessary.

- *) In order to account for the various compilers, E, e, D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.
Zero-padded two-digit exponents are required, however.

TABLE A5			
METEOROLOGICAL DATA FILE - HEADER SECTION DESCRIPTION			
HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT	
RINEX VERSION / TYPE	- Format version (2.12)	F9.2,11X,	
	- File type ('M' for Meteorological Data)	A1,39X	
PGM / RUN BY / DATE	- Name of program creating current file	A20,	
	- Name of agency creating current file	A20,	
	- Date of file creation	A20	
* COMMENT	Comment line(s)	A60	*
MARKER NAME	Station Name	A60	
	(preferably identical to MARKER NAME in		
	the associated Observation File)		
* MARKER NUMBER	Station Number	A20	*
	(preferably identical to MARKER NUMBER in		
	the associated Observation File)		

# / TYPES OF OBSERV	- Number of different observation types stored in the file	I6,
	- Observation types	9 (4X, A2)
	The following meteorological observation types are defined in RINEX Version 2:	
	PR : Pressure (mbar)	
	TD : Dry temperature (deg Celsius)	
	HR : Relative humidity (percent)	
	ZW : Wet zenith path delay (mm) (for WVR data)	
	ZD : Dry component of zenith path delay (mm)	
	ZT : Total zenith path delay (mm)	
	WD : Wind azimuth (deg) from where the wind blows	
	WS : Wind speed (m/s)	
	RI : "Rain increment" (1/10 mm): Rain accumulation since last measurement	
	HI : Hail indicator: 1 = Hail detected since last measurement	
	The sequence of the types in this record must correspond to the sequence of the measurements in the data records	
	If more than 9 observation types are being used, use continuation lines including header label in cols. 61-80!	6X, 9 (4X, A2)
<hr/>		
SENSOR MOD/TYPE/ACC	Description of the met sensor	
	- Model (manufacturer)	A20,
	- Type	A20, 6X,
	- Accuracy (same units as obs values)	F7.1, 4X,
	- Observation type	A2, 1X
Record is repeated for each observation type found in # / TYPES OF OBSERV record		
<hr/>		

SENSOR POS XYZ/H	Approximate position of the met sensor	
	- Geocentric coordinates X, Y, Z (ITRF	3F14. 4,
	- Ellipsoidal height H or WGS-84)	1F14. 4,
	- Observation type	1X, A2, 1X
	Set X, Y, Z to zero if not known.	
	Make sure H refers to ITRF or WGS-84!	
	Record required for barometer,	
	recommended for other sensors.	
+-----+		
END OF HEADER	Last record in the header section.	60X
+-----+		

Records marked with * are optional

+-----+		
TABLE A6		
METEOROLOGICAL DATA FILE - DATA RECORD DESCRIPTION		
+-----+		
OBS. RECORD	DESCRIPTION	FORMAT
+-----+		
EPOCH / MET	- Epoch in GPS time (not local time!)	
	year (2 digits, padded with 0 if necessary)	1X, I2. 2,
	month, day, hour, min, sec	5(1X, I2),
	The 2-digit years in RINEX Version 1 and 2. xx	
	files are understood to represent	
	80-99: 1980-1999 and 00-79: 2000-2079	
	- Met data in the same sequence as given in the	mF7. 1
	header	
	More than 8 met data types: Use continuation	4X, 10F7. 1, 3X
	lines	
+-----+		

+-----+		
TABLE A7		
GPS OBSERVATION DATA FILE - EXAMPLE		
+-----+		

+-----+-----+-----+-----+-----+-----+-----+-----+

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

```
2.12          OBSERVATION DATA      M (MIXED)          RINEX VERSION / TYPE
BLANK OR G = GPS, R = GLONASS, E = GALILEO, M = MIXED COMMENT
XXRINEXO V9.9   AIUB                   24-MAR-01 14:43    PGM / RUN BY / DATE
EXAMPLE OF A MIXED RINEX FILE COMMENT
A 9080          MARKER NAME
9080.1.34       MARKER NUMBER
BILL SMITH      ABC INSTITUTE          OBSERVER / AGENCY
X1234A123       XX                      ZZZ          REC # / TYPE / VERS
234             YY                      ANT # / TYPE
4375274.        587466.        4589095.        APPROX POSITION XYZ
.9030          .0000          .0000          ANTENNA: DELTA H/E/N
1 1            WAVELENGTH FACT L1/2
1 2 6 G14 G15 G16 G17 G18 G19 WAVELENGTH FACT L1/2
0            RCV CLOCK OFFS APPL
5 P1 L1 L2 P2 L5 # / TYPES OF OBSERV
18.000        INTERVAL
2005 3 24 13 10 36.0000000 TIME OF FIRST OBS
END OF HEADER

05 3 24 13 10 36.0000000 0 4G12G09G06E11 -.123456789
23629347.915 .300 8 -.353 23629364.158
20891534.648 -.120 9 -.358 20891541.292 -.120 9
20607600.189 -.430 9 .394 20607605.848
.324 8 .178 7
05 3 24 13 10 50.0000000 4 4
1 2 2 G 9 G12 WAVELENGTH FACT L1/2
*** WAVELENGTH FACTOR CHANGED FOR 2 SATELLITES *** COMMENT
NOW 8 SATELLITES HAVE WL FACT 1 AND 2! COMMENT
COMMENT

05 3 24 13 10 54.0000000 0 6G12G09G06R21R22E11 -.123456789
23619095.450 -53875.632 8 -41981.375 23619112.008
20886075.667 -28688.027 9 -22354.535 20886082.101
20611072.689 18247.789 9 14219.770 20611078.410
21345678.576 12345.567 5
22123456.789 23456.789 5
65432.123 5 48861.586 7
05 3 24 13 11 0.0000000 2 1
```

```

*** FROM NOW ON KINEMATIC DATA! ***
05 3 24 13 11 48.0000000 0 4G16G12G09G06 -. 123456789
21110991.756 16119.980 7 12560.510 21110998.441
23588424.398 -215050.557 6 -167571.734 23588439.570
20869878.790 -113803.187 8 -88677.926 20869884.938
20621643.727 73797.462 7 57505.177 20621649.276
3 4

```

```

A 9080 MARKER NAME
9080.1.34 MARKER NUMBER
.9030 .0000 .0000 ANTENNA: DELTA H/E/N
--> THIS IS THE START OF A NEW SITE <-- COMMENT

```

```

05 3 24 13 12 6.0000000 0 4G16G12G06G09 -. 123456987
21112589.384 24515.877 6 19102.763 3 21112596.187
23578228.338 -268624.234 7 -209317.284 4 23578244.398
20625218.088 92581.207 7 72141.846 4 20625223.795
20864539.693 -141858.836 8 -110539.435 5 20864545.943
05 3 24 13 13 1.2345678 5 0
4 1

```

```

(AN EVENT FLAG WITH SIGNIFICANT EPOCH) COMMENT
05 3 24 13 14 12.0000000 0 4G16G12G09G06 -. 123456012
21124965.133 89551.30216 69779.62654 21124972.2754
23507272.372 -212616.150 7 -165674.789 5 23507288.421
20828010.354 -333820.093 6 -260119.395 5 20828017.129
20650944.902 227775.130 7 177487.651 4 20650950.363
4 1

```

```

*** ANTISPOOFING ON G 16 AND LOST LOCK COMMENT
05 3 24 13 14 12.0000000 6 2G16G09
123456789.0 -9876543.5
0.0 -0.5
4 2

```

```

--> CYCLE SLIPS THAT HAVE BEEN APPLIED TO COMMENT
THE OBSERVATIONS COMMENT
05 3 24 13 14 48.0000000 0 4G16G12G09G06 -. 123456234
21128884.159 110143.144 7 85825.18545 21128890.7764
23487131.045 -318463.297 7 -248152.72824 23487146.149
20817844.743 -387242.571 6 -301747.22925 20817851.322
20658519.895 267583.67817 208507.26234 20658525.869
4 3

```

```

*** SATELLITE G 9 THIS EPOCH ON WLFACT 1 (L2) COMMENT
*** G 6 LOST LOCK AND THIS EPOCH ON WLFACT 2 (L2) COMMENT

```

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

```

+-----+
|                                     |
|                               TABLE A8                               |
|                               GPS NAVIGATION MESSAGE FILE - EXAMPLE   |
|                                     |
+-----+

```

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

2.12	N: GPS NAV DATA	RINEX VERSION / TYPE
XXRINEXN V2.12	AIUB	PGM / RUN BY / DATE
EXAMPLE OF VERSION 2.10 FORMAT	27-MAY-09 15:22	COMMENT
GPSA .1676D-07 .2235D-07 -.1192D-06 -.1192D-06		IONOSPHERIC CORR
GPSB .1208D+06 .1310D+06 -.1310D+06 -.1966D+06		IONOSPHERIC CORR
GPUT .1331791282D-06 .107469589D-12 552960 1025		TIME SYSTEM CORR
13		LEAP SECONDS
		END OF HEADER

6 99 9 2 17 51 44.0	-.839701388031D-03	-.165982783074D-10	.000000000000D+00
.910000000000D+02	.934062500000D+02	.116040547840D-08	.162092304801D+00
.484101474285D-05	.626740418375D-02	.652112066746D-05	.515365489006D+04
.409904000000D+06	-.242143869400D-07	.329237003460D+00	-.596046447754D-07
.111541663136D+01	.326593750000D+03	.206958726335D+01	-.638312302555D-08
.307155651409D-09	.000000000000D+00	.102500000000D+04	.000000000000D+00
.000000000000D+00	.000000000000D+00	.000000000000D+00	.910000000000D+02
.406800000000D+06	.000000000000D+00		
13 99 9 2 19 0 0.0	.490025617182D-03	.204636307899D-11	.000000000000D+00
.133000000000D+03	-.963125000000D+02	.146970407622D-08	.292961152146D+01
-.498816370964D-05	.200239347760D-02	.928156077862D-05	.515328476143D+04
.414000000000D+06	-.279396772385D-07	.243031939942D+01	-.558793544769D-07
.110192796930D+01	.271187500000D+03	-.232757915425D+01	-.619632953057D-08
-.785747015231D-11	.000000000000D+00	.102500000000D+04	.000000000000D+00
.000000000000D+00	.000000000000D+00	.000000000000D+00	.389000000000D+03
.410400000000D+06	.000000000000D+00		

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|


```

+-----+
|                                     |
|                               TABLE A9                               |
| METEOROLOGICAL DATA FILE - EXAMPLE                               |
|                                     |
+-----+

```

```

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

```

```

2.12 METEOROLOGICAL DATA RINEX VERSION / TYPE
XXRINEXM V9.9 AIUB 27-MAY-09 00:10 PGM / RUN BY / DATE
EXAMPLE OF A MET DATA FILE COMMENT
A 9080 MARKER NAME
3 PR TD HR # / TYPES OF OBSERV
PAROSCIENTIFIC 740-16B 0.2 PR SENSOR MOD/TYP/ACC
HAENNI 0.1 TD SENSOR MOD/TYP/ACC
ROTRONIC I-240W 5.0 HR SENSOR MOD/TYP/ACC
0.0 0.0 0.0 1234.5678 PR SENSOR POS XYZ/H
END OF HEADER

96 4 1 0 0 15 987.1 10.6 89.5
96 4 1 0 0 30 987.2 10.9 90.0
96 4 1 0 0 45 987.1 11.6 89.0

```

```

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

```

```

+-----+
|                                     |
|                               TABLE A10                               |
| GLONASS NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION       |
|                                     |
+-----+

```

HEADER LABEL	DESCRIPTION	FORMAT
(Columns 61-80)		
RINEX VERSION / TYPE	- Format version (2.10)	F9.2,11X,
	- File type ('G' = GLONASS nav mess data)	A1,39X
PGM / RUN BY / DATE	- Name of program creating current file	A20,
	- Name of agency creating current file	A20,
	- Date of file creation (dd-mmm-yy hh:mm)	A20
*COMMENT	Comment line(s)	A60

* TIME SYSTEM CORR	Corrections to transform the system time to UTC		*
	- Correction type	A4, 1X,	
	GLUT = GLO to UTC		
	- a0 Correction in seconds (a0=TauC)	D17. 10,	
	CORR(s) = a0	16X,	
	- T Reference time for polynomial (Seconds into GPS week)	17,	
	- W Reference week number (GPS week, continuous number)	15,	
		10X	
* LEAP SECONDS	Number of leap seconds since 6-Jan-1980	16	*
END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A11			
GLONASS NAVIGATION MESSAGE FILE – DATA RECORD DESCRIPTION			
OBS. RECORD	DESCRIPTION	FORMAT	
PRN / EPOCH / SV CLK	- Satellite number:	12,	
	Slot number in sat. constellation		
	- Epoch of ephemerides (UTC)		
	- year (2 digits, padded with 0, if necessary)	1X, 12. 2,	
	- month, day, hour, minute,	4 (1X, 12),	
	- second	F5. 1,	
	- SV clock bias (sec) (-TauN)	D19. 12,	
	- SV relative frequency bias (+GammaN)	D19. 12,	
	- message frame time (tk)	D19. 12	
	(0 .le. tk .lt. 86400 sec of day UTC)		
		*)	
	The 2-digit years in RINEX 1 and 2. xx		
	files are understood to represent		

	80-99: 1980-1999	and	00-79: 2000-2079
BROADCAST ORBIT - 1	- Satellite position X	(km)	3X, 4D19.12
	- velocity X dot	(km/sec)	
	- X acceleration	(km/sec ²)	
	- health (0=OK)	(Bn)	
BROADCAST ORBIT - 2	- Satellite position Y	(km)	3X, 4D19.12
	- velocity Y dot	(km/sec)	
	- Y acceleration	(km/sec ²)	
	- frequency number	(-7 ... +13)	
BROADCAST ORBIT - 3	- Satellite position Z	(km)	3X, 4D19.12
	- velocity Z dot	(km/sec)	
	- Z acceleration	(km/sec ²)	
	- Age of oper. information	(days) (E)	

*) In order to account for the various compilers, E, e, D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.

Zero-padded two-digit exponents are required, however.

TABLE A12
GLONASS NAVIGATION MESSAGE FILE - EXAMPLE

```

-----|-----1|0-----|-----2|0-----|-----3|0-----|-----4|0-----|-----5|0-----|-----6|0-----|-----7|0-----|-----8|
2.12          GLONASS NAV DATA          RINEX VERSION / TYPE
ASRINEXG V1.1.0  AIUB          27-MAY-09 10:42  PGM / RUN BY / DATE
STATION ZIMMERWALD          COMMENT
1998  2  16  0.379979610443D-06  CORR TO SYSTEM TIME
GLUT  .3799796104D-06  .          86400  945  TIME SYSTEM CORR
                                          END OF HEADER
3 98  2 15  0 15  0.0 0.163525342941D-03 0.363797880709D-11 0.108000000000D+05
0.106275903320D+05-0.348924636841D+00 0.931322574615D-09 0.000000000000D+00

```

```

-0.944422070313D+04 0.288163375854D+01 0.931322574615D-09 0.210000000000D+02
0.212257280273D+05 0.144599342346D+01-0.186264514923D-08 0.300000000000D+01
4 98 2 15 0 15 0.0 0.179599039257D-03 0.636646291241D-11 0.122400000000D+05
0.562136621094D+04-0.289074897766D+00-0.931322574615D-09 0.000000000000D+00
-0.236819248047D+05 0.102263259888D+01 0.931322574615D-09 0.120000000000D+02
0.762532910156D+04 0.339257907867D+01 0.000000000000D+00 0.300000000000D+01
11 98 2 15 0 15 0.0-0.559808686376D-04-0.272848410532D-11 0.108600000000D+05
-0.350348437500D+04-0.255325126648D+01 0.931322574615D-09 0.000000000000D+00
0.106803754883D+05-0.182923507690D+01 0.000000000000D+00 0.400000000000D+01
0.228762856445D+05 0.447064399719D+00-0.186264514923D-08 0.300000000000D+01
12 98 2 15 0 15 0.0 0.199414789677D-04-0.181898940355D-11 0.108900000000D+05
0.131731816406D+05-0.143945598602D+01 0.372529029846D-08 0.000000000000D+00
0.171148715820D+05-0.118937969208D+01 0.931322574615D-09 0.220000000000D+02
0.135737919922D+05 0.288976097107D+01-0.931322574615D-09 0.300000000000D+01

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

+-----+
|                                     |
|                               TABLE A13                               |
|                               GLONASS OBSERVATION FILE - EXAMPLE       |
|                                     |
+-----+

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

2.10      OBSERVATION DATA      R (GLONASS)      RINEX VERSION / TYPE
XXRINEXO V1.1      AIUB      27-AUG-93 07:23      PGM / RUN BY / DATE
TST1      MARKER NAME
VIEWEG      BRAUNSCHWEIG      OBSERVER / AGENCY
100      XX-RECEIVER      1.0      REC # / TYPE / VERS
101      XX-ANTENNA      ANT # / TYPE
3844808.114      715426.767      5021804.854      APPROX POSITION XYZ
1.2340      .0000      .0000      ANTENNA: DELTA H/E/N
1 1      WAVELENGTH FACT L1/2
2 C1 L1      # / TYPES OF OBSERV
10.000      INTERVAL
1993 8 23 14 24 40.0490000      GLO      TIME OF FIRST OBS
END OF HEADER

93 8 23 14 24 40.0490000 0 3 2R01R21
23986839.824      20520.565 5

```

```

23707804.625      19937.231 5
23834065.096      -9334.581 5
93  8 23 14 24 50.0490000  0  3  2R01R21
23992341.033      49856.525 5
23713141.002      48479.290 5
23831189.435      -24821.796 5
93  8 23 14 25  .0490000  0  3  2R01R21
23997824.854      79217.202 5
23718494.110      77092.992 5
23828329.946      -40219.918 5
93  8 23 14 25 10.0490000  0  5  2R05R17R01R21
24003328.910      108602.422 5
24933965.449      -19202.780 5
22203326.578      -2987.327 5
23723851.686      105777.849 5
23825485.526      -55529.205 5
93  8 23 14 25 20.0490010  0  5  2R05R17R01R21
24008828.023      138012.178 5
24927995.616      -51188.500 5
22202547.907      -7213.298 5
23729236.758      134533.636 5
23822662.277      -70749.590 5
93  8 23 14 25 30.0490000  0  5  2R05R17R01R21
24014330.779      167446.477 5
24922041.288      -83151.666 5
22201767.457      -11388.909 5
23734633.024      163360.131 5
23819848.894      -85881.102 5

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

+-----+
|                                     |
|                               TABLE A14                               |
|       MIXED GPS/GLONASS OBSERVATION FILE - EXAMPLE                   |
|                                     |
+-----+

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

2.12      OBSERVATION DATA      M (MIXED)      RINEX VERSION / TYPE

```

YRINEXO V2. 8. 1 VM AIUB

27-MAY-09 13:59

PGM / RUN BY / DATE

TST2

MARKER NAME

001-02-A

MARKER NUMBER

JIM

Y-COMPANY

OBSERVER / AGENCY

1 YY-RECEIVER

2. 0. 1

REC # / TYPE / VERS

1 GEODETIC L1

ANT # / TYPE

3851178. 1849 -80151. 4072 5066671. 1013

APPROX POSITION XYZ

1. 2340 0. 0000 0. 0000

ANTENNA: DELTA H/E/N

1 0

WAVELENGTH FACT L1/2

2 C1 L1

/ TYPES OF OBSERV

10. 000

INTERVAL

11

LEAP SECONDS

2000 2 6 11 53 0. 0000000 GPS

TIME OF FIRST OBS

END OF HEADER

00 2 6 11 53 0. 0000000 0 14G23G07G02G05G26G09G21R20R19R12R02R11

R10R03

22576523. 586 -11256947. 60212

22360162. 704 -16225110. 75413

24484865. 974 14662682. 882 2

21950524. 331 -13784707. 24912

22507304. 252 9846064. 848 2

20148742. 213 -20988953. 712 4

22800149. 591 -16650822. 70012

19811403. 273 -25116169. 741 3

23046997. 513 -3264701. 688 2

22778170. 622 -821857836. 745 1

22221283. 991 -988088156. 884 2

19300913. 475 -83282658. 19013

20309075. 579 -672668843. 84713

23397403. 484 -285457101. 34211

00 2 6 11 53 10. 0000000 0 14G23G07G02G05G26G09G21R20R19R12R02R11

R10R03

22578985. 016 -11244012. 910 2

22359738. 890 -16227337. 841 2

24490324. 818 14691368. 710 2

21944376. 706 -13817012. 849 2

22512598. 731 9873887. 580 2

20147322. 111 -20996416. 338 4

22798942. 949 -16657163. 594 2

19812513. 509 -25110234. 795 3

23053885.702 -3227854.397 2
 22770607.029 -821898566.774 1
 22222967.297 -988079145.989 2
 19297913.736 -83298710.38413
 20313087.618 -672647337.04113
 23392352.454 -285484291.40311

----|---1|0---|---2|0---|---3|0---|---4|0---|---5|0---|---6|0---|---7|0---|---8|

TABLE A15			
GEOSTATIONARY NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION			
HEADER LABEL (Columns 61-80)	DESCRIPTION	FORMAT	
RINEX VERSION / TYPE	- Format version (2.12)	F9.2, 11X,	
	- File type ('H' = GEO nav mess data)	A1, 39X	
PGM / RUN BY / DATE	- Name of program creating current file	A20,	
	- Name of agency creating current file	A20,	
	- Date of file creation (dd-mmm-yy hh:mm)	A20	
* COMMENT	Comment line(s)	A60	*
* TIME SYSTEM CORR	Corrections to transform the system time		*
	to UTC		
	- Correction type	A4, 1X,	
	SBUT = SBAS to UTC a0, a1		
	- a0, a1 Coefficients of 1-deg polynomial	D17.10,	
	(a0 sec, a1 sec/sec)	D16.9,	
	CORR(s) = a0 + a1*DELTAT		
	- T Reference time for polynomial	17,	
	(Seconds into GPS week)		
	- W Reference week number	15,	
	(GPS week, continuous number)		
	- S EGNOS, WAAS, or MSAS ...	1X, A5, 1X	
	(left-justified)		
	Derived from MT17 service provider.		

	If not known: Use Snn with nn = PRN-100 of satellite broadcasting the MT12		
	- U UTC Identifier (0 if unknown)	12, 1X	
	1=UTC (NIST), 2=UTC (USNO), 3=UTC (SU), 4=UTC (BIPM), 5=UTC (Europe Lab), 6=UTC (GRL), >6 = not assigned yet		
* LEAP SECONDS	Number of leap seconds since 6-Jan-1980	16	*
END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A16 GEOSTATIONARY NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION		
OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite number (PRN - 100)	12,
	- Epoch of ephemerides (GPS) (Toe)	
	- year (2 digits, padded with 0 if necessary)	1X, 12. 2,
	- month, day, hour, minute,	4 (1X, 12),
	- second	F5. 1,
	- SV clock bias (sec) (aGf0)	D19. 12,
	- SV relative frequency bias (aGf1)	D19. 12,
	- Transmission time of message (start of the message) in GPS seconds of the week	D19. 12
BROADCAST ORBIT - 1	- Satellite position X (km)	3X, 4D19. 12
	- velocity X dot (km/sec)	
	- X acceleration (km/sec ²)	*
	- health (0=OK)	
BROADCAST ORBIT - 2	- Satellite position Y (km)	3X, 4D19. 12


```

2000    1    13    14    45    0.000000    GPS    TIME OF FIRST OBS
2000    1    13    15    0    0.000000    GPS    TIME OF LAST OBS
0                                             RCV CLOCK OFFS APPL
                                             END OF HEADER

```

```

00 01 13 14 45 0.000000 0 8G25G17G06G05G24G29G30S20 0.000535140
21839900.207 -236148.877 9 -184047.71049 21839901.4384
25151926.413 -161002.900 9 -125509.72447 25151935.8274
20531103.515 763336.059 9 594797.53149 20531105.0114
23001624.801 -432989.642 9 -337436.50348 23001628.1684
23610349.510 -384890.728 9 -299952.38848 23610354.3504
23954474.398 -151982.173 9 -118480.96847 23954481.1994
20622367.016 -332628.466 9 -259214.55249 20622367.8754
38137559.506 335849.135 9

```

```

00 01 13 14 45 1.000000 0 8G25G17G06G05G24G29G30S20 0.000535144
21839500.278 -238250.743 9 -185685.52549 21839501.4814
25151246.148 -164576.503 9 -128294.33947 25151256.2614
20531084.382 763235.849 9 594719.44849 20531085.8784
23002123.430 -430369.237 9 -335394.62748 23002126.7114
23610670.127 -383205.864 9 -298639.51048 23610674.9834
23955051.773 -148948.417 9 -116117.00748 23955058.5034
20622558.579 -331621.765 9 -258430.11049 20622559.4574
38137558.783 335846.284 9

```

```

00 01 13 14 45 2.000000 0 8G25G17G06G05G24G29G30S20 0.000535144
21839100.418 -240352.173 9 -187323.00449 21839101.6534
25150565.890 -168150.148 9 -131078.97647 25150576.2144
20531065.378 763136.116 9 594641.73549 20531066.8984
23002622.082 -427748.683 9 -333352.63648 23002625.3444
23610990.819 -381520.461 9 -297326.20848 23610995.8424
23955629.062 -145914.531 9 -113752.94748 23955636.5544
20622750.161 -330614.723 9 -257645.40149 20622751.0554
38137558.365 335843.457 9

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

+-----+
|                                     |
|                               TABLE A18                               |
|                               GEO NAVIGATION MESSAGE FILE - EXAMPLE   |
|                                     |
+-----+

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

```

2.12          H: GEO NAV MSG DATA          RINEX VERSION / TYPE
SBAS2RINEX 2.0  CNES          27-MAY-09 14:01  PGM / RUN BY / DATE
SBUT .1331791282D-06 .107469589D-12 518400 1240 EGNOS 5 TIME SYSTEM CORR
13           LEAP SECONDS
This file contains navigation message data from a SBAS
(geostationary) satellite, here AOR-W (PRN 122 = # 22)
COMMENT
COMMENT
END OF HEADER

```

```

22 03 10 18 0 1 4.0-1.005828380585D-07 6.366462912410D-12 5.184420000000D+05
  2.482832392000D+04-3.593750000000D-04-1.375000000000D-07 0.000000000000D+00
-3.408920872000D+04-1.480625000000D-03-5.000000000000D-08 4.000000000000D+00
-1.650560000000D+01 8.360000000000D-04 6.250000000000D-08 2.300000000000D+01
22 03 10 18 0 5 20.0-9.872019290924D-08 5.456968210638D-12 5.186940000000D+05
  2.482822744000D+04-3.962500000000D-04-1.375000000000D-07 0.000000000000D+00
-3.408958936000D+04-1.492500000000D-03-5.000000000000D-08 4.000000000000D+00
-1.628960000000D+01 8.520000000000D-04 6.250000000000D-08 2.400000000000D+01
22 03 10 18 0 9 36.0-9.732320904732D-08 4.547473508865D-12 5.189510000000D+05
  2.482812152000D+04-4.325000000000D-04-1.375000000000D-07 0.000000000000D+00
-3.408997304000D+04-1.505000000000D-03-5.000000000000D-08 4.000000000000D+00
-1.606960000000D+01 8.800000000000D-04 6.250000000000D-08 2.500000000000D+01
22 03 10 18 0 13 52.0-9.592622518539D-08 4.547473508865D-12 5.192110000000D+05
  2.482800632000D+04-4.681250000000D-04-1.375000000000D-07 0.000000000000D+00
-3.409035992000D+04-1.518125000000D-03-3.750000000000D-08 4.000000000000D+00
-1.584240000000D+01 8.960000000000D-04 6.250000000000D-08 2.600000000000D+01

```

```

----|----1|0----|----2|0----|----3|0----|----4|0----|----5|0----|----6|0----|----7|0----|----8|

```

TABLE A19			
GALILEO NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION			
HEADER LABEL	DESCRIPTION		FORMAT
(Columns 61-80)			
RINEX VERSION / TYPE	- Format version : 2.12		F9.2,11X,
	- File type ('N' for navigation data)		A1,19X,
	- Satellite System: E: Galileo		A1,19X
PGM / RUN BY / DATE	- Name of program creating current file		A20,
	- Name of agency creating current file		A20,

	- Date and time of file creation		
	Format: <code>yyyymmdd hhmmss zone</code>	A20	
	zone: 3-4 char. code for time zone.		
	'UTC' recommended!		
	'LCL' if local time with un-		
	known local time system code		
* COMMENT	Comment line(s)	A60	*
* IONOSPHERIC CORR	Ionospheric correction parameters		*
	- Correction type	A4, 1X,	
	GAL = Galileo ai0 - ai2		
	- Parameters	4D12.4	
	GAL: ai0, ai1, ai2, zero		
* TIME SYSTEM CORR	Corrections to transform the system time		*
	to UTC or other time systems		
	- Correction type	A4, 1X,	
	GAUT = GAL to UTC a0, a1		
	- a0, a1 Coefficients of 1-deg polynomial	D17.10,	
	(a0 sec, a1 sec/sec)	D16.9,	
	CORR(s) = a0 + a1*DELTAT		
	- T Reference time for polynomial	17,	
	(Seconds into GAL week)		
	- W Reference week number	15,	
	(GAL week, continuous number)	10X	
END OF HEADER	Last record in the header section.	60X	

TABLE A20
GALILEO NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION

OBS. RECORD	DESCRIPTION	FORMAT
SV / EPOCH / SV CLK	- Satellite system (E), satellite number	A1, I2.2,
	- Epoch: Toc - Time of Clock GAL	
	- year (4 digits)	1X, I4,

	- month, day, hour, minute, second	5(1X, I2. 2),
	- SV clock bias (seconds)	af0 3D19. 12
	- SV clock drift (sec/sec)	af1
	- SV clock drift rate (sec/sec2)	af2 *)
	(see Br.Orbit-5, data source, bits 8+9)	

BROADCAST ORBIT - 1	- IODnav Issue of Data of the nav batch	4X, 4D19. 12
	- Crs (meters)	
	- Delta n (radians/sec)	***)
	- MO (radians)	

BROADCAST ORBIT - 2	- Cuc (radians)	4X, 4D19. 12
	- e Eccentricity	
	- Cus (radians)	
	- sqrt(a) (sqrt(m))	

BROADCAST ORBIT - 3	- Toe Time of Ephemeris (sec of GAL week)	4X, 4D19. 12
	- Cic (radians)	
	- OMEGA0 (radians)	
	- Cis (radians)	

BROADCAST ORBIT - 4	- i0 (radians)	4X, 4D19. 12
	- Crc (meters)	
	- omega (radians)	
	- OMEGA DOT (radians/sec)	

BROADCAST ORBIT - 5	- IDOT (radians/sec)	4X, 4D19. 12
	- Data sources (FLOAT --> INTEGER)	
	Bit 0 set: I/NAV E1-B	
	Bit 1 set: F/NAV E5a-I	
	Bit 2 set: I/NAV E5b-I	
	Bits 0-2 : non-exclusive	
	Bit 3 reserved for Galileo internal use	
	Bit 4 reserved for Galileo internal use	
	Bit 8 set: af0-af2, Toc, SISA are for E5a, E1	
	Bit 9 set: af0-af2, Toc, SISA are for E5b, E1	
	- GAL Week # (to go with Toe)	****)
	- spare	

BROADCAST ORBIT - 6	- SISA Signal in space accuracy (meters)	4X, 4D19.12
	Undefined/unknown: -1.0	
	- SV health (FLOAT converted to INTEGER)	*****)
	Bit 0: E1B DVS	
	Bits 1-2: E1B HS	
	Bit 3: E5a DVS	
	Bits 4-5: E5a HS	
	Bit 6: E5b DVS	
	Bits 7-8: E5b HS	
	- BGD E5a/E1 (seconds)	
	- BGD E5b/E1 (seconds)	
BROADCAST ORBIT - 7	- Transmission time of message **)	4X, 4D19.12
	(sec of GAL week, derived	
	from WN and TOW of page type 1)	
	- spare	
	- spare	
	- spare	

*) In order to account for the various compilers, E, e, D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files. Zero-padded two-digit exponents are required, however.

***) Adjust the Transmission time of message by + or - 604800 to refer to the reported week in BROADCAST ORBIT - 5, if necessary. Set value to 0.9999E9 if not known.

****) Angles and their derivatives transmitted in units of semi-circles and semi-circles/sec have to be converted to radians by the RINEX generator.

*****) The GAL week number is a continuous number, aligned to (and hence identical to) the continuous GPS week number used in the RINEX navigation message files. The broadcast 12-bit Galileo System Time week has a roll-over after 4095. It started at zero at the first GPS roll-over (continuous GPS week 1024). Hence GAL week = GST week + 1024 + n*4096 (n: number of GST roll-overs).

*****)

- If bit 0 or bit 2 of Data sources (BROADCAST ORBIT - 5) is set, E1B DVS &

HS, E5b DVS & HS and both BGDs are valid

- If bit 1 of Data sources is set, E5a DVS & HS and BGD E5a/E1 are valid

- Non valid parameters are set to 0 and to be ignored

TABLE A21			
QZSS NAVIGATION MESSAGE FILE - HEADER SECTION DESCRIPTION			
HEADER LABEL	DESCRIPTION	FORMAT	
(Columns 61-80)			
RINEX VERSION / TYPE	- Format version (2.12)	F9.2,11X,	
	- File type ('N' for Navigation data)	A1,19X	
	- Satellite System: J: QZSS	A1,19X	
PGM / RUN BY / DATE	- Name of program creating current file	A20,	
	- Name of agency creating current file	A20,	
	- Date of file creation	A20	
* COMMENT	Comment line(s)	A60	*
* IONOSPHERIC CORR	Ionospheric correction parameters		*
	- Correction type	A4,1X,	
	QZSA = QZS alpha0 - alpha3		
	QZSB = QZS beta0 - beta3		
	- Parameters	4D12.4	
	QZS: alpha0-alpha3 or beta0-beta3		
* ION ALPHA	Ionosphere parameters A0-A3 of almanac	2X,4D12.4	*
	(page 18 of subframe 4)		
* ION BETA	Ionosphere parameters B0-B3 of almanac	2X,4D12.4	*
* TIME SYSTEM CORR	Corrections to transform the system time		*
	to UTC		
	- Correction type	A4,1X,	
	QZGP = QZS to GPS a0, a1		
	QZUT = QZS to UTC a0, a1		
	- a0,a1 Coefficients of 1-deg polynomial	D17.10,	

	(a0 sec, a1 sec/sec)	D16.9,	
	$CORR(s) = a0 + a1*DELTA T$		
	- T Reference time for polynomial (Seconds into GPS week)	17,	
	- W Reference week number (GPS week, continuous number)	15, 10X	
* LEAP SECONDS	Delta time due to leap seconds	16	*
END OF HEADER	Last record in the header section.	60X	

Records marked with * are optional

TABLE A22		
QZSS NAVIGATION MESSAGE FILE - DATA RECORD DESCRIPTION		
OBS. RECORD	DESCRIPTION	FORMAT
PRN / EPOCH / SV CLK	- Satellite system (J), Satellite PRN-192	A1, I2,
	- Epoch: Toc - Time of Clock	
	year (2 digits, padded with 0	
	if necessary)	1X, I2.2,
	month	1X, I2,
	day	1X, I2,
	hour	1X, I2,
	minute	1X, I2,
	second	F5.1,
	- SV clock bias (seconds)	3D19.12
	- SV clock drift (sec/sec)	
	- SV clock drift rate (sec/sec2)	*)
BROADCAST ORBIT - 1	- IODE Issue of Data, Ephemeris	4X, 4D19.12
	- Crs (meters)	
	- Delta n (radians/sec)	
	- MO (radians)	
BROADCAST ORBIT - 2	- Cuc (radians)	4X, 4D19.12

	- e Eccentricity		
	- Cus	(radians)	
	- sqrt(A)	(sqrt(m))	
+-----+-----+-----+			
BROADCAST ORBIT - 3	- Toe Time of Ephemeris		4X, 4D19.12
		(sec of GPS week)	
	- Cic	(radians)	
	- OMEGA	(radians)	
	- CIS	(radians)	
+-----+-----+-----+			
BROADCAST ORBIT - 4	- i0	(radians)	4X, 4D19.12
	- Crc	(meters)	
	- omega	(radians)	
	- OMEGA DOT	(radians/sec)	
+-----+-----+-----+			
BROADCAST ORBIT - 5	- IDOT	(radians/sec)	4X, 4D19.12
	- Codes on L2 channel		
		(see IS-QZSS 5.2.2.2.3(2))	
	- GPS Week # (to go with TOE)		
		Continuous number, not mod(1024)!	
	- spare		
+-----+-----+-----+			
BROADCAST ORBIT - 6	- SV accuracy	(meters)	4X, 4D19.12
		(see IS-GPS-200, 20.3.3.3.1.3)	
	- SV health (bits 17-22 w 3 sf 1)		
		(see IS-QZSS 5.2.2.2.3(4))	
	- TGD	(seconds)	
	- IODC Issue of Data, Clock		
+-----+-----+-----+			
BROADCAST ORBIT - 7	- Transmission time of message	**)	4X, 4D19.12
		(sec of GPS week, derived e.g.	
		from Z-count in Hand Over Word (HOW)	
	- Fit interval	(hours)	
		(see IS-QZSS, 5.2.2.2.4(4))	
		Zero if not known	
	- spare		
	- spare		
+-----+-----+-----+			

***) Adjust the Transmission time of message by -604800 to refer to the

reported week, if necessary.

*) In order to account for the various compilers, E, e, D, and d are allowed letters between the fraction and exponent of all floating point numbers in the navigation message files.

Zero-padded two-digit exponents are required, however.